



Hyeonseong Kim

Address: 607 Woojung Hall of Informatics, 145 Anam-ro, Seongbuk-gu, Seoul, Republic of Korea

Phone: +82 (0)10 6502 0328

Email: hyeonseong-kim@korea.ac.kr

EDUCATION

(Expected) M.S. degree in Artificial Intelligence

Mar.2024 – Feb. 2026

Korea University, Seoul, Republic of Korea

- GPA: 4.43/4.5

B.S. degree in Mechanical Engineering

Mar. 2017 – Feb. 2024

Korea University, Seoul, Republic of Korea

- Overall GPA: 3.79/4.5
- Major GPA: 4.10/4.5

ROBOTIC PLATFORMS OPERATED (*clickable names can link to official product pages)

Main

[UR5e](#) (Manipulator): Real-time control for object handover in physical HRI experiments

[Turtlebot 4](#) (Mobile Robot): High-level decision making with VLM in navigation tasks

[Stretch 3](#) (Mobile Manipulator): Reproduced the [OK-Robot](#) system on physical hardware

Self-made Drone (UAV): Low-level control and autonomous flight for delivery scenarios

Sub

[Ambidex](#) (Upper Body Humanoid): Built smooth motion transitions for HRI state machine

[Snapbot](#) (Legged Robot): Hardware replication and locomotion experiments

SKILLS AND TECHNIQUES

Advanced - *Applied extensively with minimal supervision*

Python, ROS 2, MuJoCo Simulator

Intermediate - *Used in multiple projects with moderate guidance*

C++, Pytorch, Fusion 360, Human-subject experiment design & analysis

Fundamental - *Basic usage or coursework-level exposure*

C, Embedded System (STM32), Stereo Vision (e.g. ZED, RealSense)

INTERNATIONAL RESEARCH EXPERIENCE

Visiting Researcher, Queen's University, Canada

Mar. 2025 – Jul. 2025

PROJECTS

Joyful Deceptive Robot, *Main Researcher*

Feb. 2025 – Present

Queen's University Visiting Researcher Program

Goal: Developing playful object handover robot, inspired by Turkish ice cream vendor.

Contribution: Built the robot system that interacts with people by dodging the hand.

Dynamic Robot-to-human Handover, *Main Researcher (publication 1)*

Mar. 2024 – Sep. 2024

Korea University-Queen's University Collaboration Project

Goal: Enable seamless object transfer from robot to moving human using real-time HRI

Contribution: Designed the real-time physical HRI system with machine learning technique.

VLM-based Socially Aware Navigation, *Main Developer*

Mar. 2024 – Dec. 2024

Industry-Academia Collaborative Project with LG Electronics

Goal: Demonstrating the possibility of utilizing VLM in navigation tasks, including HRI scenario.

Contribution: Integrated ROS-based system with VLM for high-level decision and task logging.

Development of Collaborative AI Agent, *Research Member*

Apr. 2024 – Jun. 2024

Joint Research Project with ETRI

Reproduced the OK-Robot system in the real world and validated behavior modules.

Korea Robot Aircraft Competition, *Team Leader*

Apr. 2022 – Sep. 2022

Korea Aerospace Industries Association

Developed a drone for the autonomous delivery scenario.

PUBLICATIONS

1. “Learning-based Dynamic Robot-to-Human Handover” *IEEE International Conference on Robotics and Automation (ICRA) 2025* ([project page](#))

1st Author

2. "Towards Embedding Dynamic Personas in Interactive Robots: Masquerading Animated Social Kinematic (MASK)", *IEEE Robot and Automation Letters (R-AL)* 2024 ([project page](#))

3rd author

3. (Under review) "The Turkish Ice Cream Robot: Examining Playful Deception in Social Human-Robot Interactions" *IEEE International Conference on Robotics and Automation (ICRA)* 2026 ([project page](#))

1st Author

4. "Learning Rapid Adaptation of a Legged Robot under Amputation" *Asian Conference on Pattern Recognition (ACPR) 2025*

4th-Author

AWARDS & HONORS

Connected Minds Traveler Award – CAD \$6,000 research funding (hosted by Queen's & York Univ.) Jan. 2025

Silver Prize – Korea Robot Aircraft Competition Oct. 2022
